LORD DATASHEET

3DM®-CX5-15

Vertical Reference Unit (VRU)

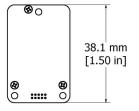


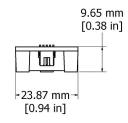
3DM-CX5-15- miniature, high-performance, industrial-grade inertial measurement unit (IMU) and vertical reference unit (VRU)

The **LORD Sensing** 3DM-CX5 family of high-performance, industrial-grade, board-level inertial sensors provides a wide range of triaxial inertial measurements and computed attitude and navigation solutions.

In all models, the Inertial Measurement Unit (IMU) includes direct measurement of acceleration and angular rate, and are fully temperature- compensated and calibrated over the operating temperature. The use of Micro- Electro- Mechanical System (MEMS) technology allows for highly accurate, small, lightweight devices.

The LORD Sensing **MIP Monitor** software can be used for device configuration, live data monitoring, and recording. Alternatively, the **MIP Data Communications Protocol** is available for development of custom interfaces and easy OEM integration.





Product Highlights

- Triaxial accelerometer, gyroscope, temperature sensors achieve the optimal combination of measurement qualities
- Dual on-board processors run a new Auto-Adaptive Extended Kalman Filter (EKF) for outstanding dynamic pitch and roll.
- Smallest, lightest, highest performance VR in its class

Features and Benefits

Best in Class Performance

- Fully calibrated, temperature-compensated, and mathematically-aligned to an orthogonal coordinate system for highly accurate outputs
- Bias tracking, error estimation, threshold flags, and adaptive noise modeling allow for fine tuning to conditions in each application
- High-performance, low-drift gyros with noise density of 0.005°/sec/√Hz and VRE of 0.001°/s/g²RMS
- Accelerometer noise as low as 25 ug/√Hz

Ease of Use

- · User-defined sensor-to-vehicle frame transformation
- Easy integration via comprehensive and fully backwardscompatible communication protocol
- Robust, forward compatible MIP packet protocol

Cost Effective

- · Out-of-the box solution reduces development time
- · Volume discounts

Applications

- · Platform stabilization, artificial horizon
- · Health and usage monitoring of vehicles

3DM-CX5-15 Vertical Reference Unit (VRU)

Specifications

General		
Triaxial accelerometer, triaxial gyroscope, temperature		
Integrated sensors	sensors, and pressure altimeter	
Data outputs	Inertial Measurement Unit (IMU) outputs: acceleration,	
	angular rate, ambient pressure, delta theta, delta	
	velocity	
	0	
	Computed outputs Extended Kalman Filter (EKF): filter status, attitude	
	estimates (Euler angles, quaternion, orientation	
	matrix), bias compensated angular rate, pressure	
	altitude, gravity-free linear acceleration, attitude	
	uncertainties, gyroscope and accelerometer bias, scale	
	factors and uncertainties, gravity models, and more.	
	Complementary Filter (CF): attitude estimates (Euler	
	angles, quaternion, orientation matrix), north and up	
	vectors, GPS correlation timestamp	
Inertial M	leasurement Unit (IMU) Sens	
	Accelerometer	Gyroscope
	10 a (atandard)	300°/sec (standard)
Measurement range	±8 g (standard) ±2 g, ±4 g, ±20 g, ±40 g	±75, ±150, ±900°
	(optional)	/sec (optional)
Non-linearity	±0.02% fs	±0.02% fs
Resolution	g (+/-8g)	
Bias instability	±0.04 mg	8°/hr
Initial bias error	±0.002 g	±0.04°/sec
Scale factor stability	±0.03%	±0.05%
Noise density		0.005°/sec/√Hz
	25 μg/√Hz (2 <i>g</i>)	(300°/sec)
Alignment error	±0.05°	±0.05°
Bandwidth	225 Hz	500 Hz
Offset error over		
temperature	0.06% (typ)	0.04% (typ)
Gain error over	0.020((+)	0.03% (typ)
temperature	0.03% (typ)	
Vibration induced noise		0.072°/s RMS/g RMS
Vibration rectification	0.03%	0.001°/s/g ² RMS
error (VRE)	0.00/0	U.UU I /S/Y NIVIO
	Digital sigma-delta wide band anti-aliasing filter to	
IMU filtering	digital averaging filter (user adjustable) scaled into	
	physical units.	Territoria
Sampling rate	1 kHz	4 kHz
IMU data output rate	AU data output rate 1 Hz to 1000 Hz	
Pressure Altimeter		
Range	-1800 m to 10,000 m	
Resolution	<0.1 m	
Noise density	0.01 hPa RMS	
Sampling rate	25 Hz	

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Computed Outputs		
Attitude accuracy	EKF outputs: ±0.25° RMS roll and pitch (typ) CF outputs: ±0.5° roll and pitch (static, typ) and ±2.0° roll and pitch (dynamic, typ)	
Attitude heading range	360° about all axes	
Attitude resolution	<0.01°	
Attitude repeatability	0.2° (typ)	
Calculation update rate	500 Hz	
Computed data output	EKF outputs: 1 Hz to 500 Hz	
rate	CF outputs: 1 Hz to 1000 Hz	
Operating Parameters		
Communication	USB 2.0 (full speed) TTL serial (3.0 V dc, 9,600 bps to 921,600 bps, default 115,200)	
Power source	+ 3.2 to 5.2 V dc	
Power consumption	500 mW (typ)	
Operating temperature	-40 °C to +85 °C	
Mechanical shock limit	500 g (calibration unaffected) 1000 g (bias may change), 5000 g (survivability)	
MTBF	(TBD)	
Physical Specifications		
Dimensions	38 mm x 24 mm x 9.7 mm	
Weight	13 grams	
Enclosure material	Aluminum	
Regulatory compliance	ROHS, CE	
	Integration	
Connectors	Data/power output: micro-DB9Samtec FTSH Series	
Software	MIP Monitor, Windows XP/Vista/7/8/10 compatible	
Compatibility	Protocol compatibility across 3DM®-GX3, GX4, RQ1, GQ4, GX5 and CV5 product families	
Software development kit (SDK)	MIP data communications protocol with sample code available (OS and platform independent)	



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